

### iQ Platform-compatible PAC Flexible High-speed I/O Control Module





# Ultrahigh-speed response asynchronous from the CPU and control bus

The MELSEC iQ-R Series is equipped with a customizable high-speed digital field programmable gate array (FPGA) I/O module. Features include the ability to program control logic and microsecond-fast asynchronous I/O response times to the programmable controller CPU and control bus, realizing stable machine performance minimizing processing speed fluctuation.

#### Enhanced I/O flexibility

The flexibility in I/O capabilities has been increased by providing 12 input points (5/24 V DC, and differential) for connecting sensors and encoders, and 14 output points (5...24 V DC: 8 outputs, and differential: 6 outputs). Wide-range of control functions including speed measurement, adjusted pulse output, ratio setting/distributed output, PWM control, and cam switch control are all possible using FPGA.

#### Improvements

- Performance asynchronous to CPU realizing microsecond-level response times
- · Lower development cost when creating complex applications
- · Replacing a microcomputer/FPGA board

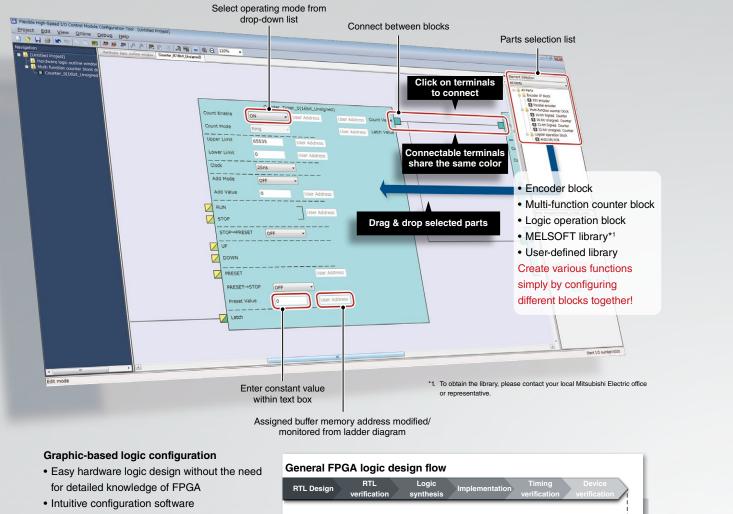
# FPGA logic design enables more freedom in customization

Equipped with a FPGA, control logic can be programmed easily using GX Works3. This low-cost alternative to HDL programming, logic synthesis and timing analysis reduces the design process, which is a common feature of general FPGA logic design.



#### Hardware logic development cost minimized

Used together with the dedicated configuration tool (integrated in GX Works3), the essential design processes associated with FPGA (HDL programming, logic synthesis and timing analysis) are no longer required, thereby reducing overall development cost.

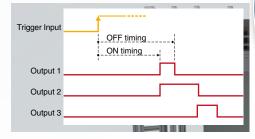


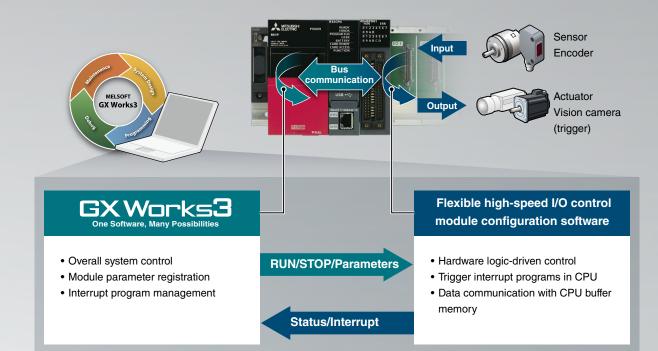
 Simple to verify logic as connection between various logic is immediately reflected Flexible high-speed I/O control module design flow
Select Connect Parameters Debug

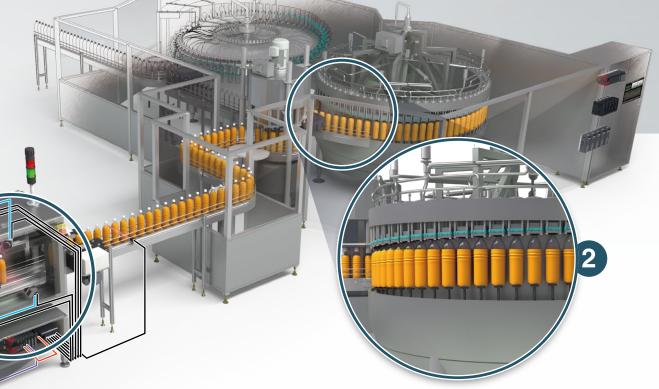
#### High-speed, stable I/O response

The flexible high-speed I/O control module provides highly accurate control of I/O timing owing to the asynchronous execution of internal control logic to the CPU and control bus. Variation in processing time is reduced to nanoseconds, thereby enabling sensors such as proximity lasers to trigger vision cameras accurately, which is required in product testing equipment in order to capture products moving at high-speed.

- Trigger input timing is adjustable to a minimum of 25 ns resolution
- Variations in processing time can be reduced to nanoseconds, enabling highly accurate control



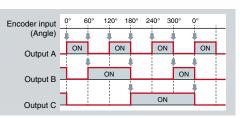




#### **2** Operation timing control replaces hardware-based mechanisms

Creation of a cam switch function is possible by the arrangement of main blocks in the configuration tool. This function can operate as a low-maintenance, high-speed alternative to mechanical camshaft control, lowering asset cost as hardware and maintenance requirements are reduced. An encoder pulse can be used for high-precision timing, such as for filling applications that require valve timing on a rotating drum.

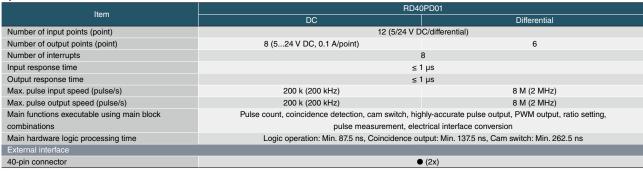
• High-precision timing control relative to each count of the encoder



#### Flexible High-speed I/O Control Module

- Further advanced inherited functions of I/O modules and high-speed counter module
- Extensive I/O and function combinations extend the application range
- $\bullet$  I/O response times reduced to less than  $1\mu s$
- · Hardware operation processing speed fluctuation reduced to nanoseconds
- · Create hardware logic without FPGA knowledge
- · Intuitive setting tool allows simple setting and connection of logic blocks
- · Verify product operation from within the configuration tool

#### Specifications



#### Main blocks\*1

Item		RD40PD01		
		DC	Differential	
External input block				
Logic select		Inverted, not inverted		
Filter time (general input)		0 µs, 10 µs, 50 µs, 0.1 ms, 0.2 ms, 0.4 ms, 0.6 ms, 1 ms, 5 ms		
Filter time (pulse input) (pulse/s)		10 k, 100 k, 200 k, 50	10 k, 100 k, 200 k, 500 k, 1 M, 2 M, 4 M, 8 M	
Parallel encoder block				
Input data type		Pure binary, gray code, BCD		
Data length		1 bit12 bits		
SSI encoder block				
Input data type		Pure binary, gray code		
Data length		1 bit32 bits		
Transmission speed		100 kHz, 200 kHz, 300 kHz, 400 kHz	100 kHz, 200 kHz, 300 kHz, 400 kHz, 500 kHz, 1.0 MHz, 1.5 MHz, 2.0 MHz	
Multi function counter b	lock			
	Туре	Addition, subtraction, linear counter m	node, ring counter mode, addition mode,	
Counter timer block		preset counter function, latch counter function, internal clock function		
	Internal clock	25 ns, 50 ns, 0.1 μs, 1 μs, 10 μs, 100 μs, 1 ms		
	Counting range	32-bit signed binary (-21474836482147483	3647), 32-bit unsigned binary (04294967295)	
		16-bit signed binary (-327683276	7), 16-bit unsigned binary (065535)	
Compare block	Compare value	Same as the counting range		
	Compare mode	=, >, <, ≥, ≤, <>		
Cam switch block (steps)			16	
Set/Reset block		Uses signal input to Set terminal as a trigger to output High fixed signal		
		Uses signal input to Reset terminal as a trigger to output Low fixed signal		
Logic operation block				
Logic operation type		AND, C	OR, XOR	
External output block				
Logic select		Inverted,	not inverted	
Delay time*2		None,12.5 ns, 25 ns, 50 ns, 0.1 µs, 1 µs, 10	μs, 100 μs, 1 ms, inter-module synchronization	

\*2. Can be set up to 64 multiples (not applicable when set to none or inter-module synchronization).

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always read the relevant manuals before use.

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